Rotary Pulse Indicator
K3HB-R

CSM_K3HB-R_DS_E_7_1

Digital Rotary Pulse Meter Capable of 50 kHz Measurements

- Measures High-speed Pulses at 50 kHz.

  Provides high-speed pulse measurements up to 50 kHz of rotary encoder or ON/OFF pulse signals and can perform rotating measurement of high-speed rotating objects.

Note: No-voltage contacts of up to 30 Hz are supported.

- Six Measurement Operations Including Rotation (rpm)/ Circumferential Speed, Ratio, and Cumulative

  One Rotary Pulse Meter has 6 rotary pulse measurement functions to support a variety of pulse measurement applications. Select the best function for your application from the following: Rotation (rpm)/ circumferential speed/instantaneous flowrate (value proportional to frequency), absolute ratio, error ratio, error, flow rate ratio, and passing speed (value inversely proportional to frequency).

⚠ Refer to *Safety Precautions for All Digital Panel Meters*.

Model Number Structure

■ Model Number Legend

Base Units and Optional Boards can be ordered individually or as sets.

Base Units

K3HB-R □ □
1 5

1. **Input Sensor Code**
   NB: NPN input/voltage pulse input
   PB: PNP input
5. **Supply Voltage**
   100-240 VAC:100 to 240 VAC
   24 VAC/VDC: 24 VAC/VDC

Optional Boards

Sensor Power Supply/Output Boards

K33-□
2

Relay/Transistor Output Boards

K34-□
3

Event Input Boards

K35-□
4

Base Units with Optional Boards

K3HB-R□-□□□ □
1 2 3 4 5

2. **Sensor Power Supply/Output Type Code**
   None: None
   CPA: Relay output (PASS: SPDT) + Sensor power supply (12 VDC±10%, 80 mA) (See note 1.)
   L1A: Linear current output (0 to 20 or 4 to 20 mA DC) + Sensor power supply (12 VDC±10%, 80 mA) (See note 2.)
   L2A: Linear voltage output (0 to 5, 1 to 5, or 0 to 10 VDC) + Sensor power supply (12 VDC±10%, 80 mA) (See note 2.)
   A: Sensor power supply (12 VDC ±10%, 80 mA)
   FLK1A: Communications (RS-232C) + Sensor power supply (12 VDC±10%, 80 mA) (See note 2.)
   FLK3A: Communications (RS-485) + Sensor power supply (12 VDC±10%, 80 mA) (See note 2.)
3. **Relay/Transistor Output Type Code**
   None: None
   C1: Relay contact (H/L: SPDT each)
   C2: Relay contact (HH/H/LL/L: SPST-NO each)
   T1: Transistor (NPN open collector: HH/H/PASS/L/LL)
   T2: Transistor (PNP open collector: HH/H/PASS/L/LL)
   BCD*: BCD output + transistor output (NPN open collector: HH/H/PASS/L/LL)
   DRT: DeviceNet (See note 2.)
   * A Special BCD Output Cable (sold separately) is required.
4. **Event Input Type Code**
   None: None
   1: 5 inputs (M3 terminal blocks), NPN open collector
   2: 8 inputs (10-pin MIL connector), NPN open collector
   3: 5 inputs (M3 terminal blocks), PNP open collector
   4: 8 inputs (10-pin MIL connector), PNP open collector

Note: 1. CPA can be combined with relay outputs only.
2. Only one of the following can be used by each Digital Indicator: RS-232C/RS-485 communications, BCD communications, or DeviceNet communications.

Accessories (Sold Separately)

K32-DICN: Special Cable (for event inputs with 8-pin connector)
K32-BCD: Special BCD Output Cable

Rubber Packing

Model
K32-P1

Note: Rubber packing is provided with the Controller.

Specifications

■ Ratings

Supply voltage		100 to 240 VAC, 24 VAC/VDC, DeviceNet power supply: 24 VDC
Allowable power supply voltage range		85% to 110% of the rated power supply voltage, DeviceNet power supply: 11 to 25 VDC
Power consumption (See note 1.)		100 to 240 VAC: 18 VA max. (max. load) 24 VAC/DC: 11 VA/7 W max. (max. load)
Current consumption		DeviceNet power supply: 50 mA max. (24 VDC)
Input		No-voltage contact, voltage pulse, open collector
External power supply		12 VDC ±10%, 80 mA (models with external power supply only)
Event inputs (See note 2.)	**Startup compensation timer input**	NPN open collector or no-voltage contact signal ON residual voltage: 2 V max. ON current at 0 Ω: 4 mA max. Max. applied voltage: 30 VDC max. OFF leakage current: 0.1 mA max.
	Hold input	
	Reset input	
	Bank input	
Output ratings (depends on the model)	**Relay output**	250 VAC, 30 VDC, 5 A (resistive load) Mechanical life expectancy: 5,000,000 operations, Electrical life expectancy: 100,000 operations
	Transistor output	Maximum load voltage: 24 VDC, Maximum load current: 50 mA, Leakage current: 100 μA max.
	Linear output	Linear output 0 to 20 mA DC, 4 to 20 mA DC: Load: 500 Ω max, Resolution: Approx. 10,000, Output error: ±0.5% FS Linear output 0 to 5 VDC, 1 to 5 VDC, 0 to 10 VDC: Load: 5 kΩ max, Resolution: Approx. 10,000, Output error: ±0.5% FS (1 V or less: ±0.15 V; no output for 0 V or less)
Display method		Negative LCD (backlit LED) display 7-segment digital display (Character height: PV: 14.2 mm (green/red); SV: 4.9 mm (green))
Main functions		Scaling function, measurement operation selection, averaging, output hysteresis, output OFF delay, output test, teaching, display value selection, display color selection, key protection, bank selection, display refresh period, maximum/minimum hold, reset
Ambient operating temperature		−10 to 55°C (with no icing or condensation)
Ambient operating humidity		25% to 85%
Storage temperature		−25 to 65°C (with no icing or condensation)
Altitude		2,000 m max.
Accessories		Watertight packing, 2 fixtures, terminal cover, unit stickers, instruction manual. DeviceNet models also include a DeviceNet connector (Hirose HR31-5.08P-5SC(01)) and crimp terminals (Hirose HR31-SC-121) (See note 3.)

Note: 1. DC power supply models require a control power supply capacity of approximately 1 A per Unit when power is turned ON. Particular attention is required when using two or more DC power supply models. The OMRON S8VS-series DC Power Supply Unit is recommended.

2. PNP input types are also available.

3. For K3HB-series DeviceNet models, use only the DeviceNet Connector included with the product. The crimp terminals provided are for Thin Cables.

■ Characteristics

Display range		−19,999 to 99,999
Measurement accuracy (at 23±5°C)		Functions F1, F6: ±0.006% rgd ±1 digit (for voltage pulse/open collector sensors) Functions F2 to F5: ±0.02% rgd ±1 digit (for voltage pulse/open collector sensors)
Measurement range		Functions F1 to F6: 0.5 mHz to 50 kHz (for voltage pulse/open collector sensors)
Input signals		Contact input (dry contact input) (30-Hz max. with ON/OFF pulse width of 15 ms min.) No contact voltage pulse (50-KHz max. with ON/OFF pulse width of 9 μs min.; ON voltage: 4.5 to 30 V; OFF voltage: −30 to 2 V; input impedance: 10 kΩ) Open collector (50-KHz max. with ON/OFF pulse width of 9 μs min.)
Connectable sensors		ON residual voltage: 3 V max. OFF leakage current: 1.5 mA max. Load current: Must have a switching capacity of 20 mA or higher. Must be able to properly switch load currents of 5 mA or less.
Comparative output response time (transistor output)		Functions F1 to F6: 100 ms max. (time until the comparative output is made when there is a forced sudden change in the input signal from 15% to 95% or 95% to 15%.)
Linear output response time		Functions F1 to F6: 110 ms max. (time until the final analog output value is reached when there is a forced sudden change in the input signal from 15% to 95% or 95% to 15%.)
Insulation resistance		20 MΩ min. (at 500 VDC)
Dielectric strength		2,300 VAC for 1 min between external terminals and case
Noise immunity		100 to 240 VAC models: ±1,500 V at power supply terminals in normal or common mode (waveform with 1-ns rising edge and pulse width of 1 μs/100 ns) 24 VAC/VDC models: ±1,500 V at power supply terminals in normal or common mode (waveform with 1-ns rising edge and pulse width of 1 μs/100 ns)
Vibration resistance		Frequency: 10 to 55 Hz; Acceleration: 50 m/s^2, 10 sweeps of 5 min each in X, Y, and Z directions
Shock resistance		150 m/s^2 (100 m/s^2 for relay outputs) 3 times each in 3 axes, 6 directions
Weight		Approx. 300 g (Base Unit only)
Degree of protection	**Front panel**	Conforms to NEMA 4X for indoor use (equivalent to IP66)
	Rear case	IP20
	Terminals	IP00 + finger protection (VDE0106/100)
Memory protection		EEPROM (non-volatile memory) Number of rewrites: 100,000
Applicable standards		UL61010C-1, CSA C22.2 No. 1010.1 (evaluated by UL) EN61010-1 (IEC61010-1): Pollution degree 2/Overvoltage category II EN61326: 1997, A1: 1998, A2: 2001
EMC		EMI: EN61326 industrial applications Electromagnetic radiation interference CISPR 11 Group 1, Class A Terminal interference voltage CISPR 11 Group 1, Class A EMS: EN61326 industrial applications Electrostatic Discharge Immunity EN61000-4-2: 4 kV (contact), 8 kV (in air) Radiated Electromagnetic Field Immunity EN61000-4-3: 10 V/m 1 kHz sine wave amplitude modulation (80 MHz to 1 GHz, 1.4 to 2 GHz) Electrical Fast Transient/Burst Noise Immunity EN61000-4-4: 2 kV (power line), 1 kV (I/O signal line) Surge Immunity EN61000-4-5: 1 kV with line (power line), 2 kV with ground (power line) Conducted Disturbance Immunity EN61000-4-6: 3 V (0.15 to 80 MHz) Power Frequency Magnetic Immunity EN61000-4-8: 30 A/m (50 Hz) continuous time Voltage Dips and Interruptions Immunity EN61000-4-11: 0.5 cycle, 0°/180°, 100% (rated voltage)

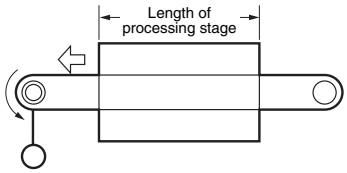
Operation

■ Functions (Operating Modes)

F1 to F6

Functions F1 to F6 provide rpm/circumferential speed and other calculation displays by measuring continuous pulses (frequencies).

Example



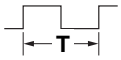
Function name	Function No.
Rpm/circumferential speed	F1
Absolute ratio	F2
Error ratio	F3
Rotational difference	F4
Flow rate ratio	F5
Passing time	F6

F1: Displays rotation (rpm) or circumferential speed for one input.

F2 to F5: Displays the calculation result for two rotation (rpm) speeds.

F6: Displays the passing time calculated from the circumferential speed and the length of the processing stage for one input.

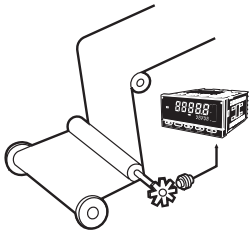
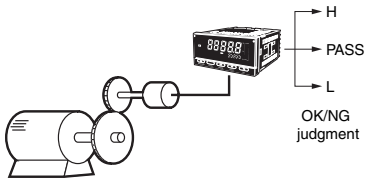
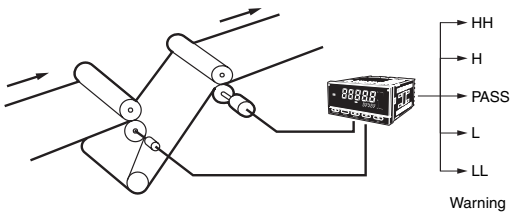
The basic principle used by the Digital Indicator to calculate the rotation speed (rpm) display is to count the ON/OFF time (T) for input sensor or other device inputs using the internal system clock, and then automatically calculate the frequency. This frequency (f) is multiplied by 60 and displayed as the rotation (rpm) speed.

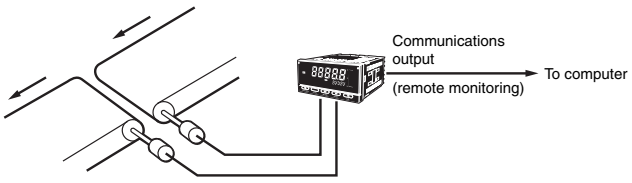
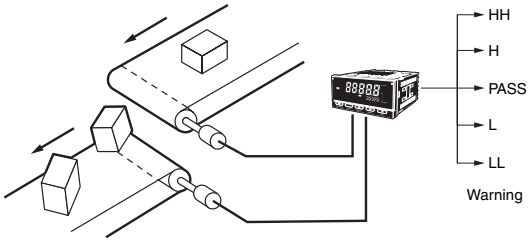
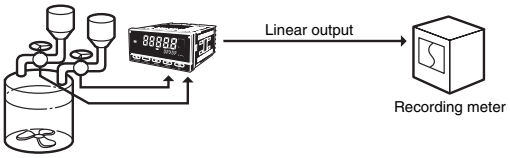
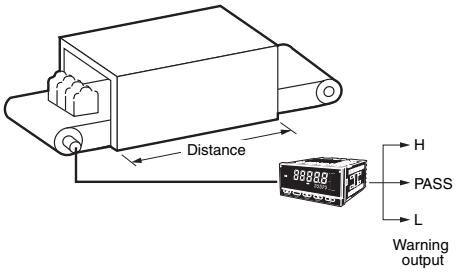
Input sensor or other input pulse ON/OFF time (T) = 

Frequency (f) = $\frac{1}{T}$

- Rotation speed (rpm) = f × 60
- Circumferential speed = Roll circumference × Rotation speed (rpm)
- Passing time= $\frac{\text{Length of processing stage}}{\text{Circumferential speed}}$

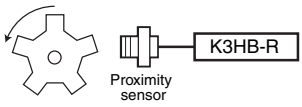
These calculations are automatically made internally and displayed whenever any input pulse is received.

<table>
<tr><th>Function</th><th>Operation</th><th>Operation image (application)</th></tr>
<tr><td>F1
Rpm/ circumfer-ential speed/ Instanta-neous flowrate</td><td>Measures frequency for input A and displays the rotation (rpm) or circumferential speed proportional to the input frequency.
Display value D = fa × 60 × α fa: Input frequency (Hz)
<table>
<tr><th>Calculation</th><th>Display unit</th><th>Prescale value (α)</th></tr>
<tr><td rowspan="2">Rotation speed</td><td>rpm</td><td>1/N</td></tr>
<tr><td>rps</td><td>1/60 N</td></tr>
<tr><td rowspan="2">Frequency (of input pulse)</td><td>Hz</td><td>1/60</td></tr>
<tr><td>kHz</td><td>1/60000</td></tr>
<tr><td rowspan="5">Circumfer-ential speed</td><td>mm/s</td><td>1000 πd/60 N</td></tr>
<tr><td>cm/s</td><td>100 πd/60 N</td></tr>
<tr><td>m/s</td><td>πd/60 N</td></tr>
<tr><td>m/min</td><td>πd/N</td></tr>
<tr><td>km/h</td><td>0.06 πd/N</td></tr>
<tr><td rowspan="2">Instanta-neous flowrate</td><td>ℓ/min</td><td rowspan="2">Check the output specifications of the input device and calculate the prescale value from the following equation:
Display value D = fa × 60 × α</td></tr>
<tr><td>ℓ/h</td></tr>
</table>
N = Pulses per rotation
πd = Circumferential length per rotation (m)</td><td>Measuring roller winding speed
 
Measuring motor speed (for product testing)
 
</td></tr>
<tr><td>F2
Absolute ratio</td><td>Multiples input B divided by input A ($\frac{B}{A}$) by 100 and displays the ratio as a percentage (%).
Display unit: %</td><td>Measuring the speed ratio between two rollers
 
</td></tr>
</table>

Function	Operation	Operation image (application)
F3 Error ratio	Multiplies the error between input A and input B ($\frac{B}{A}-1$) by 100 and displays the ratio as a percentage (%). Display unit: %	Measuring the line speed error ratio between two conveyors 
F4 Rotational difference	Displays the difference between input A and input B (B − A) as the rotation (rpm) speed error or circumferential speed error. (Display unit: rpm, rps, rph, Hz, kHz, mm/s, m/s m/min, km/h l/min, l/h, etc.)	Measuring the rotation (rpm)/circumferential speed error (absolute error) between two conveyors 
F5 Flow rate ratio	Displays the flow rate ratio of B from inputs A and B ($\frac{B}{A+B}$) as a ratio (%). Display unit: %	Monitoring liquid mixture flow rate ratio 
F6 Passing time	The passing time for the desired distance is displayed by measuring the frequency of input A. Passing time (s) = $1/fa \times \alpha$ fa: Input frequency (Hz) Set the prescale value for the desired display unit using the following table for reference. <table><tr><th>Calculation</th><th>Display unit</th><th>Prescale value (α)</th></tr><tr><td>Passing time</td><td>s</td><td>L/(πd/N)</td></tr></table> N = Pulses per rotation πd = Circumferential length per rotation (m) L = Length of process (m) (Display unit: Seconds (s), minutes (min), hours/minutes/seconds (h.min.s), minutes/seconds/tenths of seconds (min.s.1/10s), etc.)	Displaying the passing time for a conveyor line 

■ What Is Prescaling?

To make calculations using the input pulse to display rotation (rpm) or circumferential speed, the number of pulses per rotation or the length of the circumference must be multiplied by a certain coefficient. This coefficient is called the prescale value.



Rotation speed (rpm) = f × 60 × a

f: Input pulse frequency (No. of pulses per second)

a: Prescale value

If there are 5 pulses per rotation, then

a = 1/5 (= 0.2 = 2×10^{-1})

and an accurate rotation speed (rpm) can be calculated.

The actual setting is X = 2.0000 (mantissa) and Y = 10^{-1} (exponent).

■ What Is the Auto-zero Function?

(Set this function before using the Digital Indicator.)

If a function F1 to F6 is set, the frequency can be force-set to zero if there is no input pulse for a set period. This period is called the auto-zero time. Set the auto-zero time to slightly longer than the longest input pulse interval. (The display will not easily return to zero if the auto-zero time is too long or left at the default setting.)

Time Unit Settings

Setting	Meaning
SCAL	Prescale value menu setting
oCn	Minute display
H.mm.SS	h.mm.ss display
mm.SS.d	mm.ss.d display (d = tenths of a second)

Note: Time unit can be set only when passing time (F6) is selected.

Input Type Setting

	NO: Voltage pulse high	NC: Voltage pulse low
No-contact or voltage pulse input	00	01
Contact	10	11

Note: Set to 10 or 11 when there is a large variation in the display. The largest measurement range is 30 Hz.

Common Specifications

■ Event Input Ratings

K3HB-R	S-TMR, HOLD, RESET, BANK1, BANK2, BANK4	
Contact	ON: 1 kΩ max., OFF: 100 kΩ min.	
No-contact	ON residual voltage:	2 V max.
	OFF leakage current:	0.1 mA max.
	Load current:	4 mA max.
	Maximum applied voltage:	30 VDC max.

■ Output Ratings

Contact Output

Item	Resistive loads (250 VAC, cosϕ=1; 30 VDC, L/R=0 ms)	Inductive loads (250 VAC, closed circuit, cosϕ=0.4; 30 VDC, L/R=7 ms)
Rated load	5 A at 250 VAC 5 A at 30 VDC	1 A at 250 VAC 1 A at 30 VDC
Mechanical life expectancy	5,000,000 operations	
Electrical life expectancy	100,000 operations	

Transistor Outputs

Maximum load voltage	24 VDC
Maximum load current	50 mA
Leakage current	100 μA max.

Linear Output

Item / Outputs	0 to 20 mA	4 to 20 mA	0 to 5 V	1 to 5 V	0 to 10 V
Allowable load impedance	500 Ω max.		5 kΩ min.		
Resolution	Approx. 10,000				
Output error	±0.5% FS		±0.5% FS (±0.15 V for 1 V or less and no output for 0 V)		

Serial Communications Output

Item / Type	RS-232C, RS-485
Communications method	Half duplex
Synchronization method	Start-stop synchronization (asynchronous)
Baud rate	9600/19200/38400 bps
Transmission code	ASCII
Data length	7 bits or 8 bits
Stop bit length	2 bits or 1 bit
Error detection	Vertical parity and FCS
Parity check	Odd, even

BCD Output I/O Ratings (Input Signal Logic: Negative)

I/O signal name		Item		Rating
Inputs	REQUEST HOLD MAX MIN RESET	Input signal		No-voltage contact input
		Input current for no-voltage input		10 mA
		Signal level	ON voltage	1.5 V max.
			OFF voltage	3 V min.
Outputs	DATA POLARITY OVER DATA VALID RUN	Maximum load voltage		24 VDC
		Maximum load current		10 mA
		Leakage current		100 μA max.
	HH H PASS L LL	Maximum load voltage		24 VDC
		Maximum load current		50 mA
		Leakage current		100 μA max.

Refer to the *K3HB Communications User's Manual* (Cat. No. N129) for details on serial and DeviceNet communications.

DeviceNet Communications

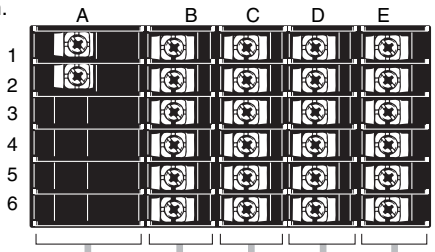
<table>
<tr><td colspan="2">Communications protocol</td><td>Conforms to DeviceNet</td></tr>
<tr><td rowspan="3">Supported communications</td><td>Remote I/O communications</td><td>Master-Slave connection (polling, bit-strobe, COS, cyclic)
Conforms to DeviceNet communications standards.</td></tr>
<tr><td>I/O allocations</td><td>Allocate any I/O data using the Configurator.
Allocate any data, such as DeviceNet-specific parameters and variable area for Digital Indicators.
Input area: 2 blocks, 60 words max.
Output area: 1 block, 29 words max.
(The first word in the area is always allocated for the Output Execution Enabled Flags.)</td></tr>
<tr><td>Message communications</td><td>Explicit message communications
CompoWay/F communications commands can be executed
(using explicit message communications)</td></tr>
<tr><td colspan="2">Connection methods</td><td>Combination of multi-drop and T-branch connections (for trunk and drop lines)</td></tr>
<tr><td colspan="2">Baud rate</td><td>DeviceNet: 500, 250, or 125 Kbps (automatic follow-up)</td></tr>
<tr><td colspan="2">Communications media</td><td>Special 5-wire cable (2 signal lines, 2 power supply lines, 1 shield line)</td></tr>
<tr><td colspan="2">Communications distance</td><td>
<table>
<tr><th>Baud rate</th><th>Network length (max.)</th><th>Drop line length (max.)</th><th>Total drop line length (max.)</th></tr>
<tr><td>500 Kbps</td><td>100 m max.
(100 m max.)</td><td>6 m max.</td><td>39 m max.</td></tr>
<tr><td>250 Kbps</td><td>100 m max.
(250 m max.)</td><td>6 m max.</td><td>78 m max.</td></tr>
<tr><td>125 Kbps</td><td>100 m max.
(500 m max.)</td><td>6 m max.</td><td>156 m max.</td></tr>
</table>
The values in parentheses are for Thick Cable.
</td></tr>
<tr><td colspan="2">Communications power supply</td><td>24-VDC DeviceNet power supply</td></tr>
<tr><td colspan="2">Allowable voltage fluctuation range</td><td>11 to 25-VDC DeviceNet power supply</td></tr>
<tr><td colspan="2">Current consumption</td><td>50 mA max. (24 VDC)</td></tr>
<tr><td colspan="2">Maximum number of nodes</td><td>64 (DeviceNet Configurator is counted as one node when connected.)</td></tr>
<tr><td colspan="2">Maximum number of slaves</td><td>63</td></tr>
<tr><td colspan="2">Error control checks</td><td>CRC errors</td></tr>
<tr><td colspan="2">DeviceNet power supply</td><td>Supplied from DeviceNet communications connector</td></tr>
</table>

Connections

■ External Connection Diagrams

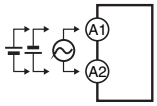
Terminal Arrangements

Note: Refer to *Internal Block Diagram* on page 12 for information on isolation.



A Operating Power Supply

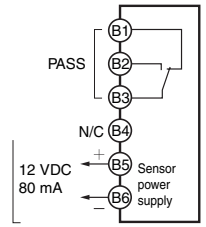
100 to 240 VAC
24 VAC/VDC



*Check the required power supply type.

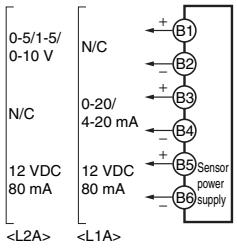
B Sensor Power Supply/Output

Sensor power supply + PASS output



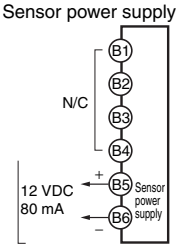
<CPA>

Sensor power supply + linear output



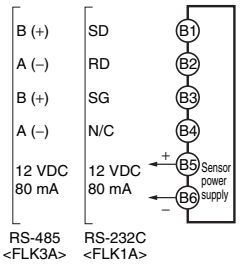
<L2A> <L1A>

Sensor power supply



<A>

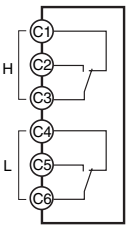
Sensor power supply + communications



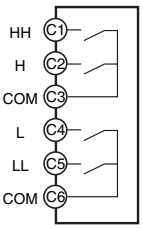
RS-485 <FLK3A>
RS-232C <FLK1A>

C Relays, Transistors, BCD and DeviceNet

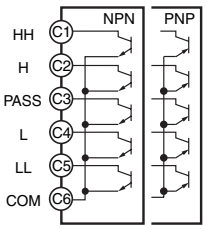
Relay Outputs <C1>



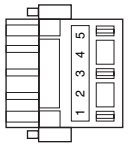
Relay Outputs <C2>



Transistor Outputs <T1> <T2>

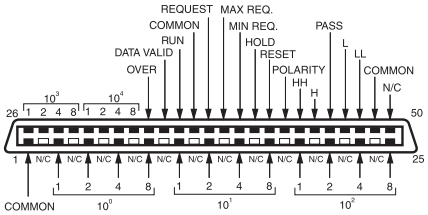


DeviceNet Connector (Included) <DRT>



1: V– (Power supply cable: Black)
2: CAN L (Communications cable: Blue)
3: Shield
4: CAN H (Communications cable: White)
5: V+ (Power supply cable: Red)
Applicable Connector:
HR31-5.08P-5SC (01)
(HIROSE ELECTRIC CO., LTD.)
* Attach the provided crimp terminals.

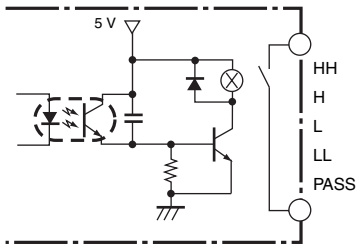
BCD (NPN Open Collector): <BCD>
Applicable Connector (Sold separately)
K32-BCD (OMRON)
(HDR-E50MAG1 with 0.3-m cable)



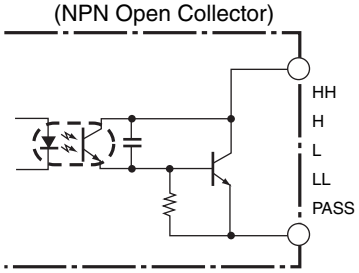
The BCD COMMON is shared.
The pins indicated in the above diagram as blank (white) boxes have been removed.

* Only one of the following can be used for each Digital Indicator: communications, BCD, or DeviceNet.

Contact Outputs



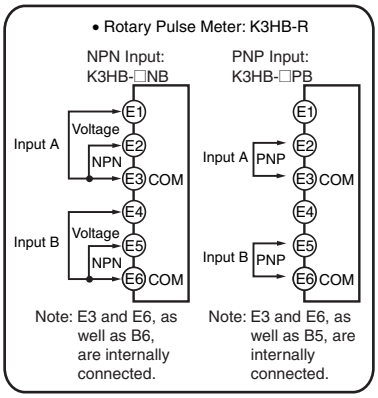
Transistor Outputs (NPN Open Collector)



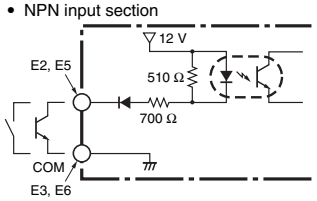
Safety Standards Conformance

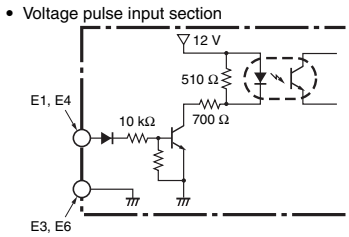
- Always use a EN/IEC-compliant power supply with reinforced insulation or double insulation for the DeviceNet power supply.
- The product must be used indoors for the above applicable standards to apply.

E Pulse Inputs

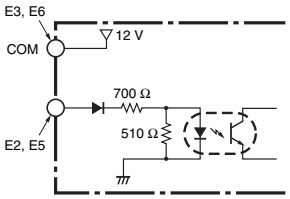


NPN Input Model

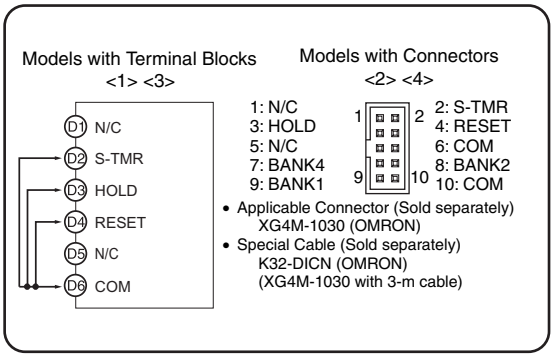




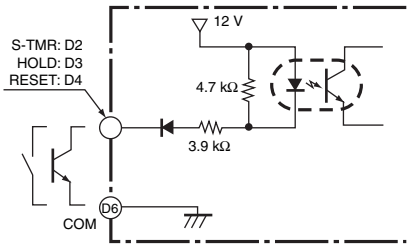
PNP Input Model



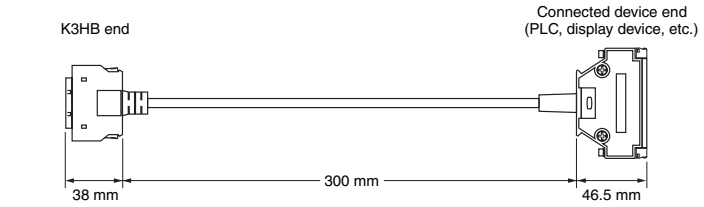
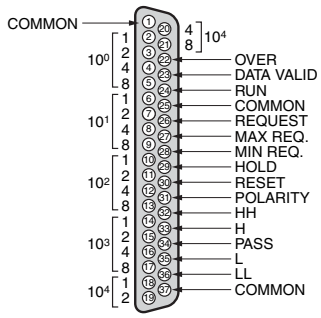
D Event Inputs



- Use terminal pin D6 as the common terminal.
- Use NPN open collector or no-voltage contacts for event input.
  PNP types are also available.



BCD Output Cable

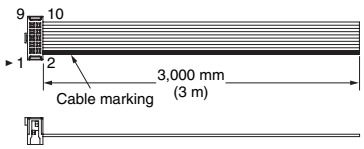
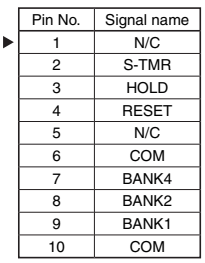
Model	Shape	Pin arrangement
K32-BCD		

Cover: HDR-E50LPA5
(manufactured by Honda Tsushin Co., Ltd.)
Connector: HDR-E50MAG1
(manufactured by Honda Tsushin Co., Ltd.)

D-sub connector (37-pin female)
Cover: 17JE-37H-1A (manufactured by DDK)
Connector: Equivalent to 17JE-13370-02
(manufactured by DDK)
Stud: 17L-002A (manufactured by DDK)

Note: The BCD Output Cable has a D-sub plug. Cover: 17JE-37H-1A (manufactured by DDK); Connector: equivalent to 17JE-23370-02 (D1) (manufactured by DDK)

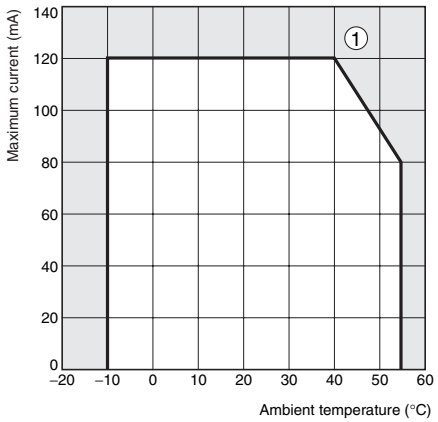
Special Cable (for Event Inputs with 8-pin Connector)

Model	Appearance	Wiring
K32-DICN		

Pin No.	Signal name
1	N/C
2	S-TMR
3	HOLD
4	RESET
5	N/C
6	COM
7	BANK4
8	BANK2
9	BANK1
10	COM

■ Derating Curve for Sensor Power Supply (Reference Values)

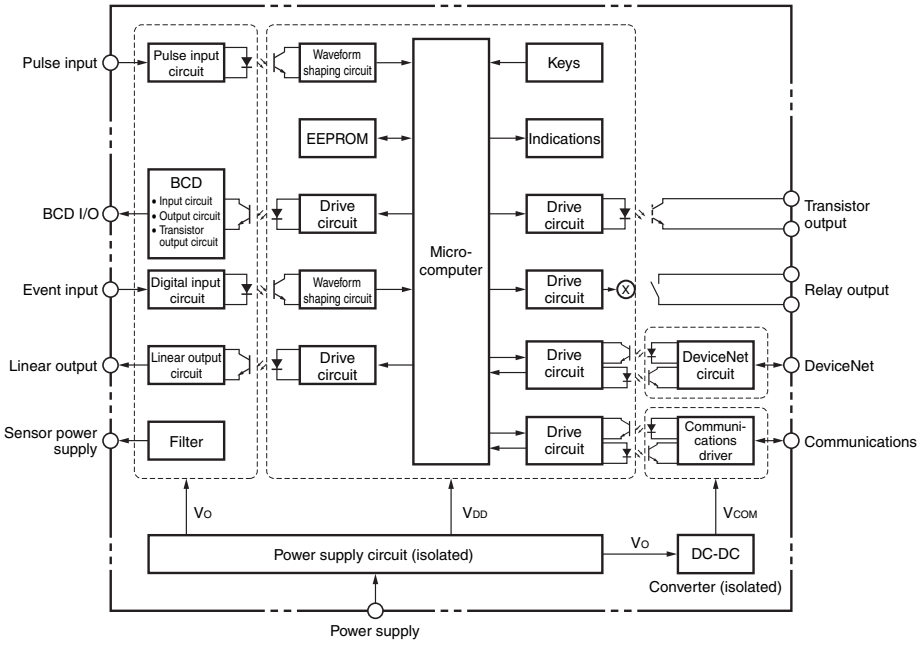
For 12V



Note: 1. The above values were obtained under test conditions with the standard mounting. The derating curve will vary with the mounting conditions, so be sure to adjust accordingly.

2. Internal components may be deteriorated or damaged. Do not use the Digital Indicator outside of the derating range (i.e., do not use it in the area labeled ①, above).

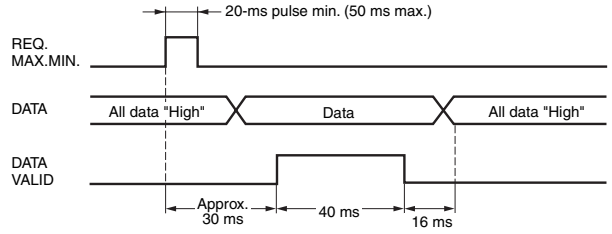
■ Internal Block Diagram



■ BCD Output Timing Chart

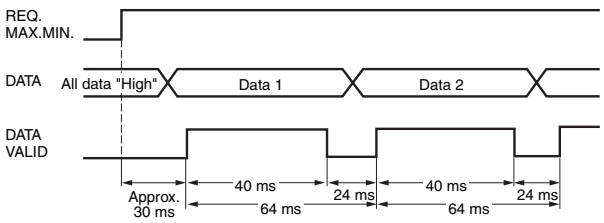
A REQUEST signal from a Programmable Controller or other external device is required to read BCD data.

Single Sampling Data Output



The data is set in approximately 30 ms from the rising edge of the REQUEST signal and the DATA VALID signal is output.
When reading the data from a Programmable Controller, start reading the data when the DATA VALID signal turns ON.
The DATA VALID signal will turn OFF 40 ms later, and the data will turn OFF 16 ms after that.

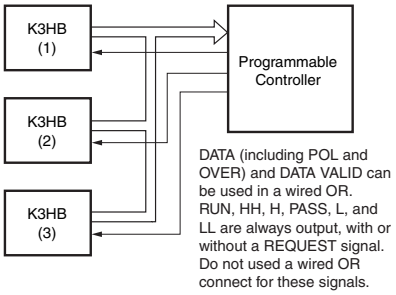
Continuous Data Output

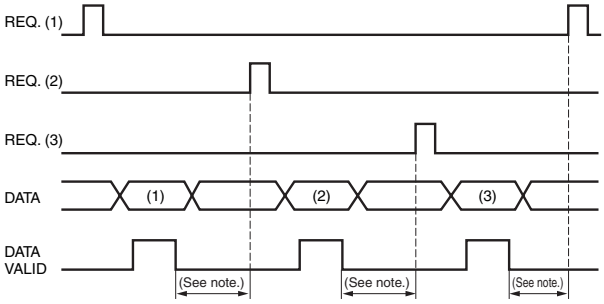


Measurement data is output every 64 ms while the REQUEST signal remains ON.

Note: If HOLD is executed when switching between data 1 and data 2, either data 1 or data 2 is output depending on the timing of the hold signal. The data will not go LOW.

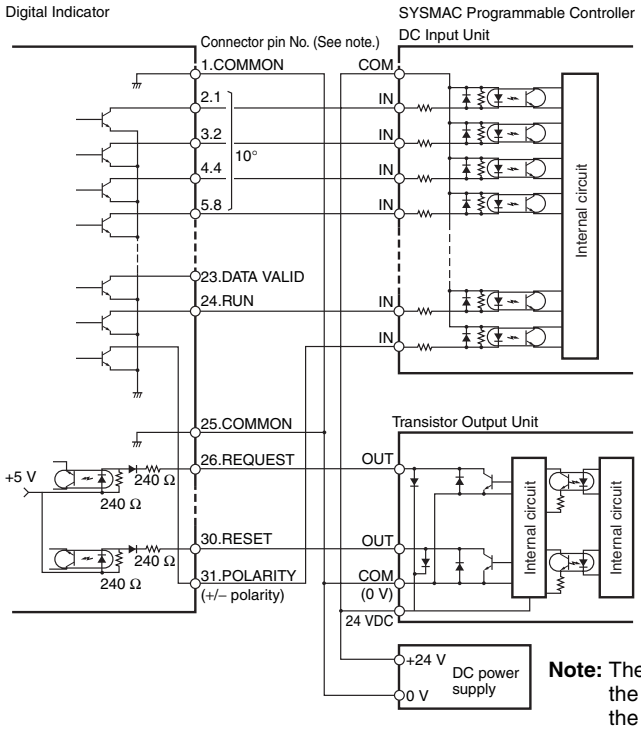
• The K3HB BCD output model has an open collector output, so wired OR connection is possible



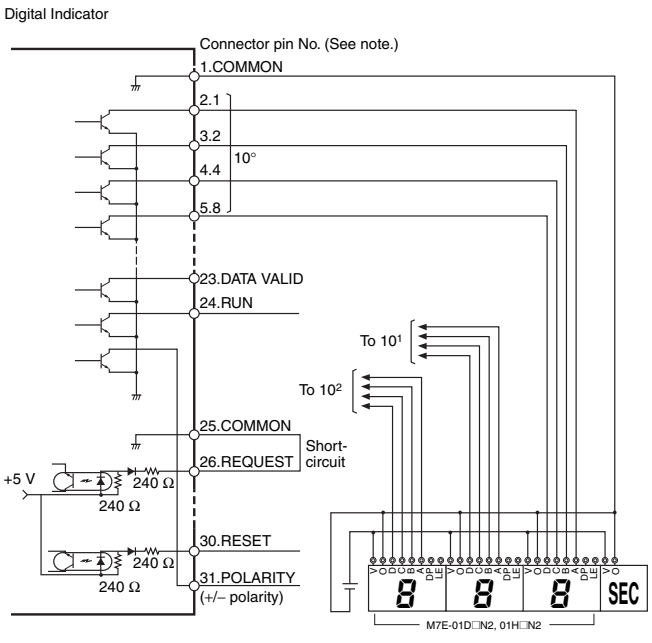


Note: Leave 20 ms min. between DATA VALID turning OFF and the REQUEST signal.

Programmable Controller Connection Example



Display Unit Connection Example



<M7E Digital Display Unit>

Note: The BCD output connector pin number is the D-sub connector pin number when the BCD Output Cable (sold separately) is connected. This number differs from the pin number for the Digital Indicator narrow pitch connector (manufactured by Honda Tsushin Kogyo Co., Ltd.).

Refer to the following User's Manual for application precautions and other information required when using the Digital Indicator:
K3HB-R/P/C Digital Indicator User's Manual (Cat. No. N136)
The manual can be downloaded from the following site in PDF format: OMRON Industrial Web http://www.fa.omron.co.jp

■ Component Names and Functions

Max./Min. status indicator

Turns ON when the maximum value or minimum value is displayed in the RUN level.

Level/bank display

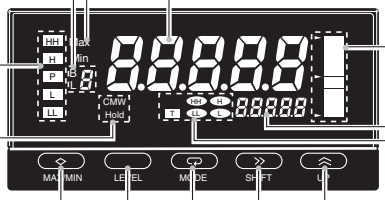
In RUN level, displays the bank if the bank function is ON. (Turns OFF if the bank function is OFF.)
In other levels, displays the current level.

Comparative output status indicators

Display the status of comparative outputs.

Status indicators

Display	Function
CMW	Lit when communications writing is ON (enabled) and not lit when OFF (prohibited).
Hold	Turns ON/OFF when HOLD input turns ON/OFF.



PV display

Displays PVs, maximum values, minimum values, parameter names, and error names.

Position meter

Displays the position of the PV with respect to a desired scale.

SV display

Displays SV and monitor values.

SV display status indicators

Indicator	Function
T	Turns ON when parameters for which teaching can be performed are displayed.
HH, H, L, LL	In RUN level, turn ON when the comparative set value HH, H, L, or LL is displayed.

MAX/MIN Key

Used to switch the display between the PV, maximum value, and minimum value and to reset the maximum and minimum values.

LEVEL Key

Used to switch level.

MODE Key

Used to switch the parameters displayed.

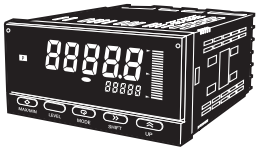
SHIFT Key

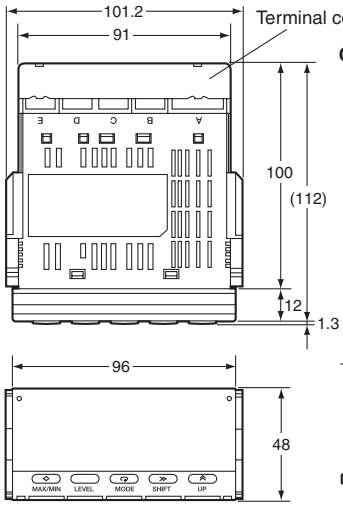
Used to change parameter settings.
When changing a set value, this key is used to move along the digits.

UP Key

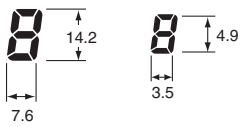
When changing a set value, this key is used to change the actual value.
When a measurement value is displayed, this key is used to execute or clear the forced-zero function or to execute teaching.

■ Dimensions

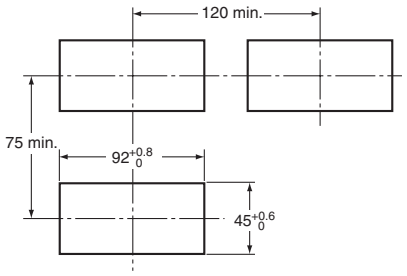




Character Size for Main Display (mm)



Panel Cutout Dimensions



Mounting Recommended Panel Thickness
1 to 8 mm.
Mount the product horizontally.

*DeviceNet models: 97 mm

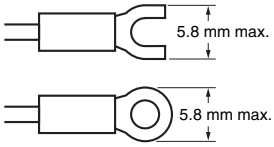
Terminal: M3, Terminal Cover: Accessory

Wiring Precautions

- For terminal blocks, use the crimp terminals suitable for M3 screws.
- Tighten the terminal screws to the recommended tightening torque of approx. 0.5 N·m.
- To prevent inductive noise, separate the wiring for signal lines from that for power lines.

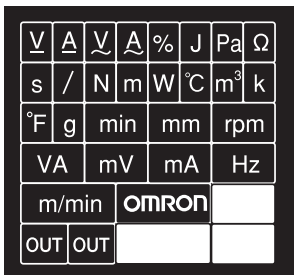
Wiring

- Use the crimp terminals suitable for M3 screws shown below.



Unit Stickers (included)

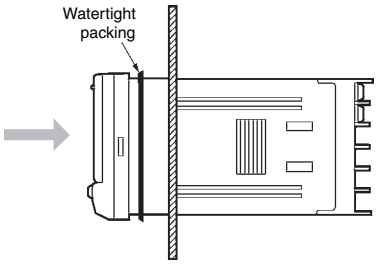
- No unit stickers are attached to the Digital Indicator.
- Select the appropriate units from the unit sticker sheets provided.



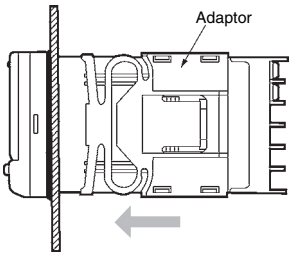
Note: For measurements for commercial purposes, be sure to use the unit required by any applicable laws or regulations.

Mounting Method

1. Insert the K3HB into the mounting cutout in the panel.
2. Insert watertight packing around the Unit to make the mounting watertight.

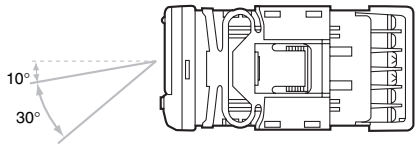


3. Insert the adapter into the grooves on the left and right sides of the rear case and push until it reaches the panel and is fixed in place.



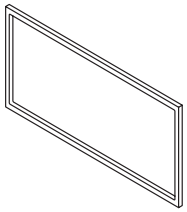
LCD Field of Vision

The K3HB is designed to have the best visibility at the angles shown in the following diagram.



Rubber Packing (Sold Separately)

K32-P1



If the rubber packing is lost or damaged, it can be ordered using the following model number: K32-P1.

(Depending on the operating environment, deterioration, contraction, or hardening of the rubber packing may occur and so, in order to ensure the level of waterproofing specified in NEMA4, periodic replacement is recommended.)

Note: Rubber packing is provided with the Controller.

Main Functions

■ Main Functions and Features

Measurement

Function FUnC

The K3HB-R has the following six functions for receiving and displaying input pulses.

F1: Rotation (rpm)/circumferential speed

F2: Absolute ratio

F3: Error ratio

F4: Rotational difference

F5: Flow rate ratio

F6: Passing time

The K3HB-P has the following six functions for receiving and displaying input pulses.

F1: Passing speed

F2: Cycle

F3: Time difference

F4: Time band

F5: Measuring length

F6: Interval

The K3HB-C has the following three functions for receiving and displaying input pulses.

F1: Individual inputs

F2: Phase differential inputs

F3: Pulse counting input

Filters

Average Processing AuG-t, AuG-n

Average processing of input signals with extreme changes or noise smooths out the display and makes control stable.

Input Types in-tA, in-tb

Specify the types of sensor connected to input A and input B.

Input Compensation

Auto-zero Times At.3A, At.3b

The frequency is forced to zero if there is no pulse input for a set period.

Key Operations

Teaching

The present measurement value can be used as a scaling value.

Key Protection

Key protection restricts level or parameter changes using the keys to prevent unintentional key operations and malfunctions.

Outputs

Comparative Output Pattern oUt-P

Standard, zone, and level comparative output patterns can be selected for comparative outputs.

Hysteresis HYS

Prevents comparative outputs from chattering when the measurement value fluctuates slightly near the set value.

Output Refresh Stop o-StP

Holds the output status when a comparative result output other than PASS turns ON.

PASS Output Change PASS

Comparative results other than PASS and error signals can be output from the PASS output terminal.

Output OFF Delay oFF-d

Delays turning OFF comparatives for a set period. This can be used to provide sufficient time to read the comparative output ON status when the comparative result changes at short intervals.

Shot Output SHot

Turns ON the comparative output for a specific time.

Output Logic oUt-n

Reverses the output logic of comparative results.

Startup Compensation Timer S-tnr

Measurements can be stopped for a set time using an external input.

Output Test tESt

Output operation can be checked without using actual input signals by using the keys to set a test measurement value.

Linear Outputs LSEtC, LSEtA, LSEtH, LSEtL

A current or voltage proportional to the change in the measurement value can be output.

Standby Sequence Stdby

The comparison outputs can be kept OFF until the measurement value enters the PASS range.

Display

Display Value Selection diSP

The display value can be set to the present value, the maximum value, or the minimum value.

Display Color Selection CoLor

The present value display color can be set to green or red. The color of the present value can also be switched according to the comparative output.

Display Refresh Period drEF

When the input changes rapidly, the display refresh period can be lengthened to control flickering and make the display easier to read.

Position Meter PoS-t, PoS-H, PoS-L

The present measurement value can be displayed as a position in relation to the scaling width on a 20-gradation position meter.

Prescale PSAu, PSAY, PSbu, PSbY

The input signal can be converted and displayed as any value.

Comparative Set Value Display Su.dSP

Select whether or not to display the comparative value during operation.

Display auto-return rEt

Automatically returns the display to RUN level when there are no key operations (e.g., max./min. switching, bank settings using keys).

Other

Max./Min. Hold

Holds the maximum and minimum measurement values.

Bank Selection bnK-C

Switch between 8 comparative value banks using the keys on the front panel or external inputs. A set of set comparative values can be selected as a group.

Bank Copy CoPY

Any bank settings can be copied to all banks.

ALL DIMENSIONS SHOWN ARE IN MILLIMETERS.
To convert millimeters into inches, multiply by 0.03937. To convert grams into ounces, multiply by 0.03527.

In the interest of product improvement, specifications are subject to change without notice.